# Siamese Network: Architecture and Applications in Computer Vision

Tech Report

Dec 30, 2014

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## Outline

- Metric Learning
- Siamese Architecture
- Siamese Network: Applications in computer vision
- Triplet Network
- Conclusion

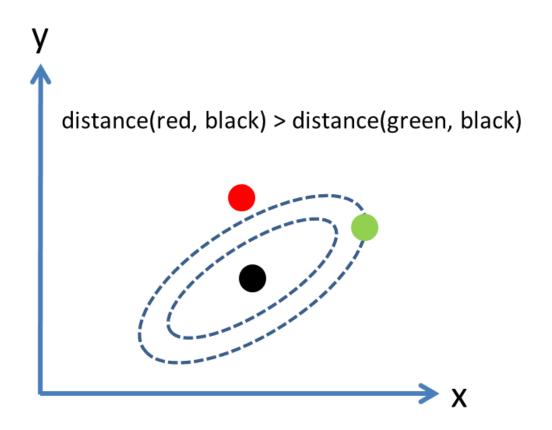
## Siamese

- Someone or something from Thailand:
  - The Thai language, The Thai people

- Siamese, an informal term for conjoined or fused:
  - Siamese twins, conjoined twins
  - Siamesing (engineering), the practice, whose name is derived from siamese twins, of combining two devices (such as cylinder ports or cooling jackets) together into a closely coupled pair, so as to save space between them.

# Metric Learning

• Euclidean distance vs Mahalanobis distance



# Metric Learning

Mahalanobis Distance Metric Learning

- Euclidean distance
- Mahalanobis distance  $d(\vec{x}, \vec{y}) = \sqrt{(\vec{x} \vec{y})^T S^{-1} (\vec{x} \vec{y})}$ .
- Mahalanobis Distance Metric Learning

$$d(x,y) = d_{A}(x,y) = ||x - y||_{A} = \sqrt{(x - y)^{T} A(x - y)}$$

$$\min_{A} \sum_{(x_{i},x_{j}) \in \mathcal{S}} ||x_{i} - x_{j}||_{A}^{2}$$
s.t. 
$$\sum_{(x_{i},x_{j}) \in \mathcal{D}} ||x_{i} - x_{j}||_{A} \ge 1$$

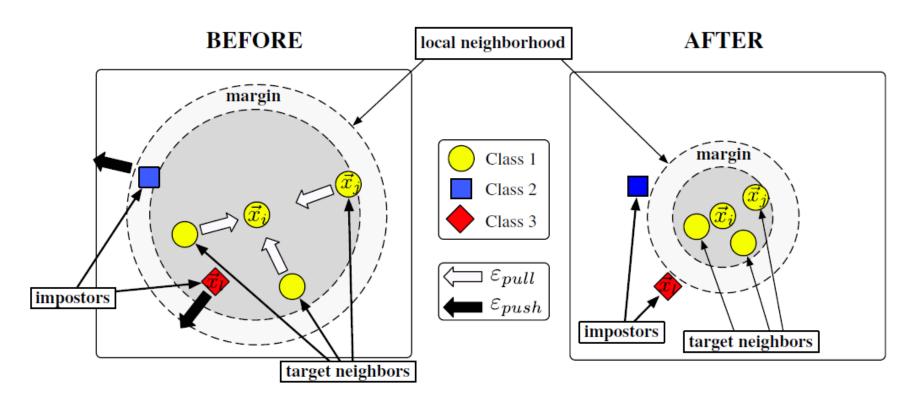
$$A \succeq 0$$

Xing E P, Jordan M I, Russell S, et al. Distance metric learning with application to clustering with side-information[C], NIPS2002: 505-512.

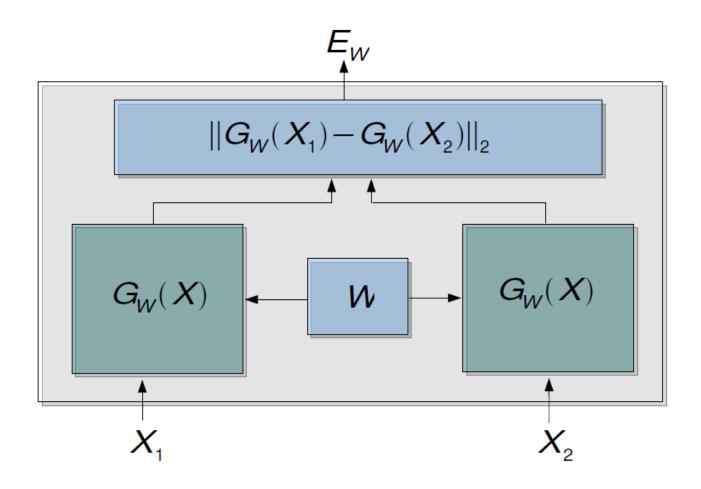
## Metric Learning

Large-Margin Nearest Neighbors(LMNN)

$$\min_{A\succeq 0} \sum_{(i,j)\in\mathcal{S}} d_A(\boldsymbol{x}_i,\boldsymbol{x}_j) + \lambda \sum_{(i,j,k)\in\mathcal{R}} [1 + d_A(\boldsymbol{x}_i,\boldsymbol{x}_j) - d_A(\boldsymbol{x}_i,\boldsymbol{x}_k)]_+$$

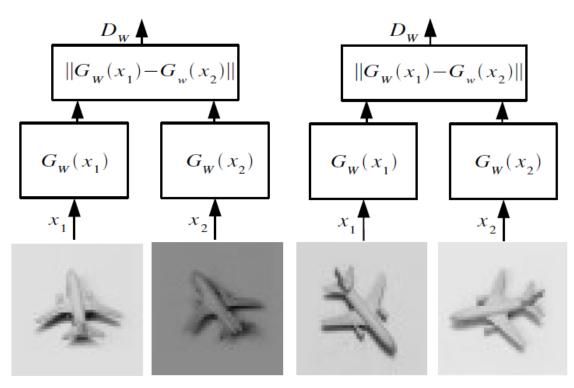


## Siamese Architecture



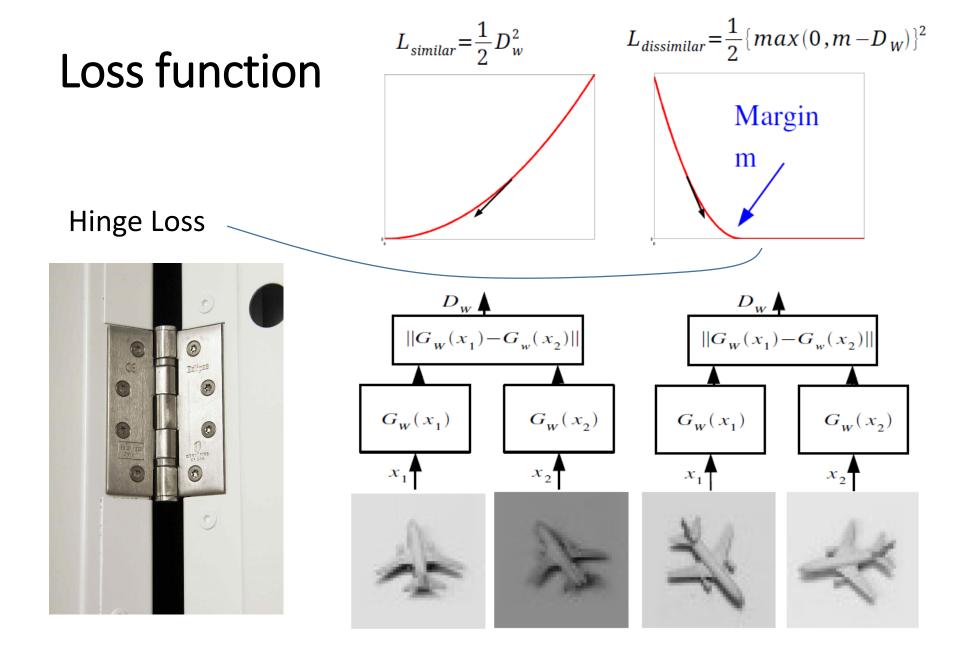
#### Siamese Architecture and loss function

#### Make this small Make this large



Similar images (neighbors in the neighborhood graph)

Dissimilar images (non-neighbors in the neighborhood graph)

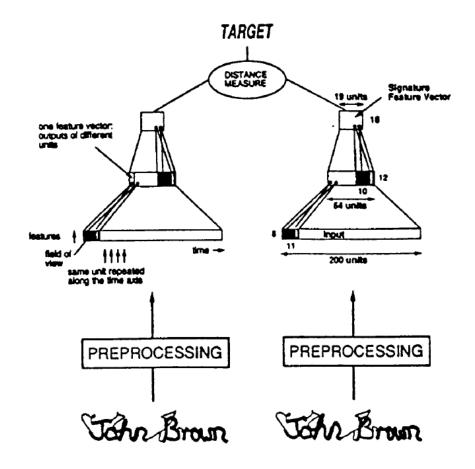


Learning Hierarchies of Invariant Features. Yann LeCun. helper.ipam.ucla.edu/publications/gss2012/gss2012 10739.pdf

#### Application in Signature Verification

The input is 8(feature)
 x 200(time) units.

 The cosine distance was used, (1 for genuine pairs, -1 for forgery pairs)

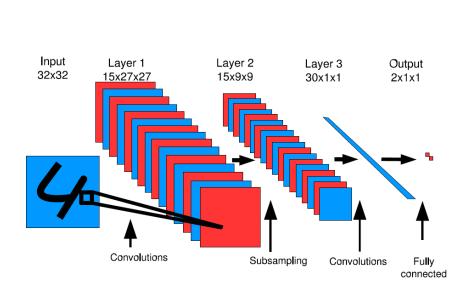


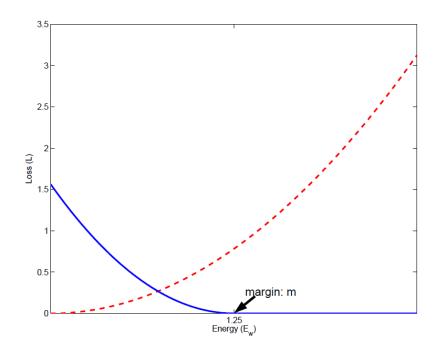
Bromley J, Guyon I, Lecun Y, et al. Signature Verification using a" Siamese" Time Delay Neural Network, NIPS Proc. 1994.

#### Application in Dimensionality reduction

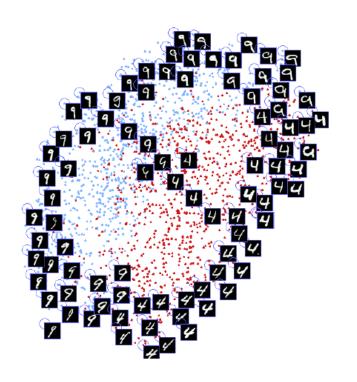
The exact loss function is

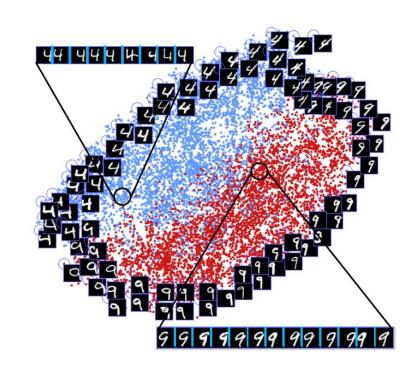
$$L(W, Y, \vec{X_1}, \vec{X_2}) = (1 - Y)\frac{1}{2}(D_W)^2 + (Y)\frac{1}{2}\{max(0, m - D_W)\}^2$$





#### Application in Dimensionality reduction

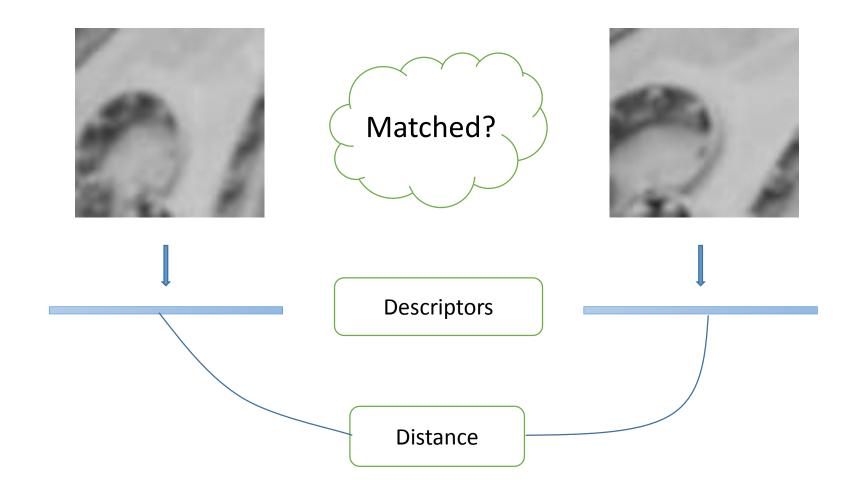




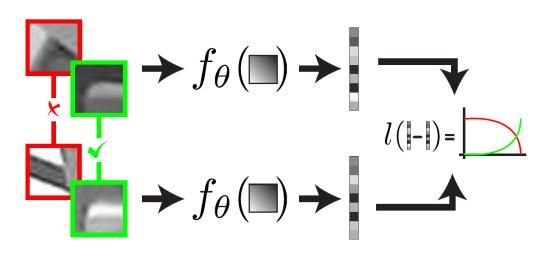
LearnedMapping of MNIST samples

Learning a Shift Invariant Mapping of MNIST samples

# **Image Descriptors**



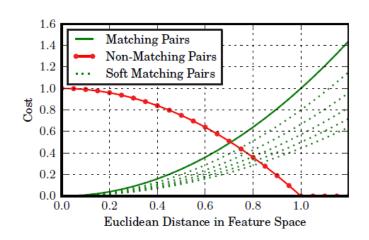
## Application in Learning Image Descriptors ( I )





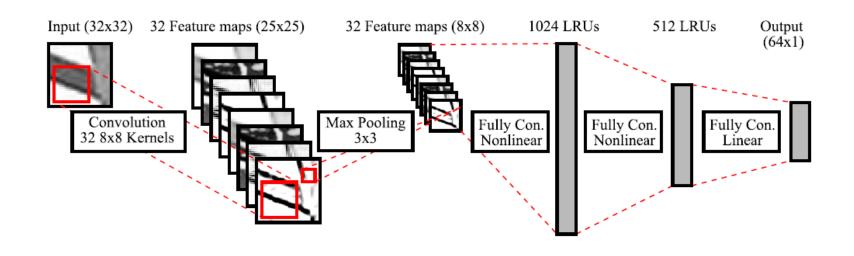
Using the contrastive cost function

$$l_{\theta}\left(\mathbf{y}_{i}, \mathbf{y}_{j}\right) = \begin{cases} s_{ij}d_{ij}^{2}, & \text{if matching} \\ \max\left(1.0 - d_{ij}^{2}, 0\right), & \text{if non-matching} \end{cases}$$



Nicholas Carlevaris-Bianco and Ryan M. Eustice, Learning visual feature descriptors for dynamic lighting conditions. In Proceedings of the IEEE/RSJ International Conference on Intelligent Robots and Systems, 2014

#### Application in Learning Image Descriptors (I)



**CNN Model** 

Nicholas Carlevaris-Bianco and Ryan M. Eustice, Learning visual feature descriptors for dynamic lighting conditions. In Proceedings of the IEEE/RSJ International Conference on Intelligent Robots and Systems, 2014

#### Application in Learning Image Descriptors ( $I\!I$ )

$$d_D(\mathbf{x}_1, \mathbf{x}_2) = \|D(\mathbf{x}_1) - D(\mathbf{x}_2)\|_2$$

$$l(\mathbf{x}_1, \mathbf{x}_2, \delta) = \delta \cdot l_P(d_D(\mathbf{x}_1, \mathbf{x}_2)) + (1 - \delta) \cdot l_N(d_D(\mathbf{x}_1, \mathbf{x}_2))$$

$$l_P(d_D(\mathbf{x}_1, \mathbf{x}_2)) = d_D(\mathbf{x}_1, \mathbf{x}_2)$$

$$l_N(d_D(\mathbf{x}_1, \mathbf{x}_2)) = \max(0, m - d_D(\mathbf{x}_1, \mathbf{x}_2))$$

$$l(\mathbf{x}_1, \mathbf{x}_2, \delta)$$

$$l(\mathbf{x}_1, \mathbf{x}_2, \delta)$$

Fracking Deep Convolutional Image Descriptors, Under review as a conference paper at ICLR 2015, <a href="http://arxiv.org/abs/1412.6537">http://arxiv.org/abs/1412.6537</a>

Convolutional Neural Networks learn compact local image descriptors, http://arxiv.org/abs/1304.7948

# Face recognition

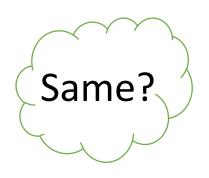
#### 1. Face identification

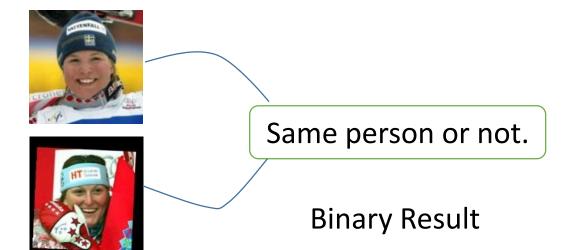




Multiclass classification

#### 2. Face verification





Α

В

## Application in face verification (I)

Let  $X_1$  and  $X_2$  be a pair of images shown to our learning machine. Let Y be a binary label of the pair, Y = 0 if the images  $X_1$  and  $X_2$  belong to the same person (a "genuine pair") and Y = 1 otherwise (an "impostor pair").

We assume that the loss function depends on the input and the parameters only indirectly through the energy. Our loss function is of the form:

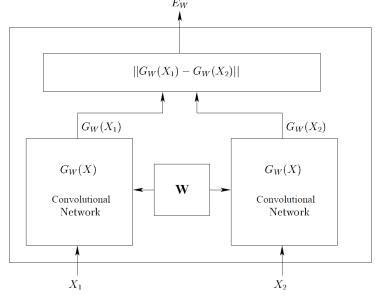
$$\mathcal{L}(W) = \sum_{i=1}^{P} L(W, (Y, X_1, X_2)^i)$$

$$L(W, (Y, X_1, X_2)^i) = (1 - Y)L_G \left( E_W(X_1, X_2)^i \right)$$

$$+ YL_I \left( E_W(X_1, X_2)^i \right)$$

$$= (1 - Y)\frac{2}{Q} (E_W)^2 + (Y)2Q e^{-\frac{2.77}{Q}E_W}$$

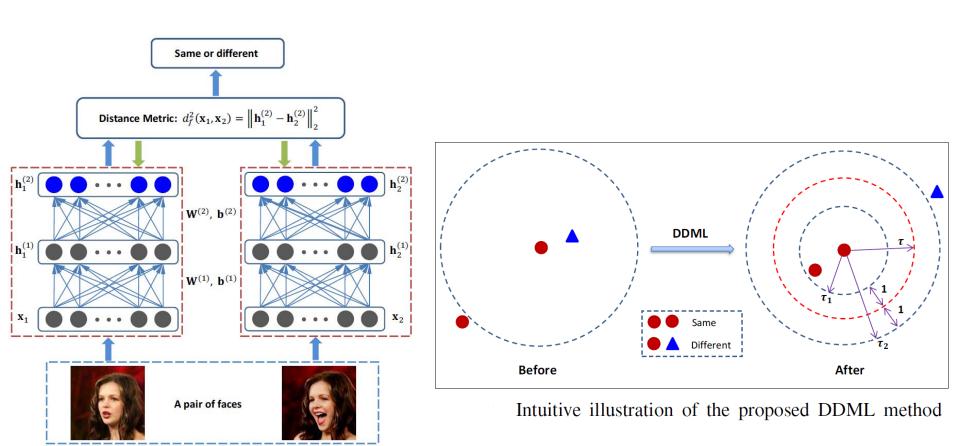
$$E_W = ||G_W(X_1) - G_W(X_2)||$$



Chopra S, Hadsell R, LeCun Y. Learning a similarity metric discriminatively, with application to face verification, CVPR 2005

#### Application in face verification (II)

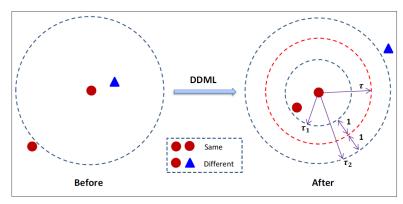
LFW:90.68%



## Application in face verification( II )

$$d_f^2(x_i, x_j) < \tau - 1, l_{ij} = 1$$
  
$$d_f^2(x_i, x_j) > \tau + 1, l_{ij} = -1$$

$$\ell_{ij} \left( \tau - d_f^2(\mathbf{x}_i, \mathbf{x}_j) \right) > 1$$



Intuitive illustration of the proposed DDML method

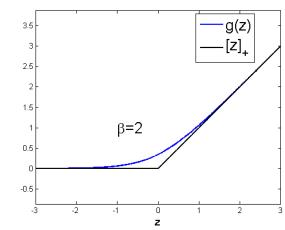
DDML as the following optimization problem:

$$\arg \min_{f} J = J_1 + J_2 \qquad \text{the hid}$$

$$= \frac{1}{2} \sum_{i,j} g \left( 1 - \ell_{ij} \left( \tau - d_f^2(\mathbf{x}_i, \mathbf{x}_j) \right) \right)$$

+ 
$$\frac{\lambda}{2} \sum_{m=1}^{M} (\|\mathbf{W}^{(m)}\|_F^2 + \|\mathbf{b}^{(m)}\|_2^2)$$

where  $g(z) = \frac{1}{\beta} \log (1 + \exp(\beta z))$  is the generalized logistic loss function [25], which is a smoothed approximation of the hinge loss function  $[z]_+ = \max(z, 0)$ 

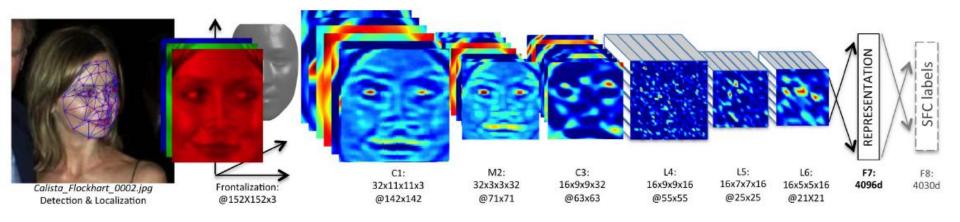


Junlin Hu, etc. Discriminative Deep Metric Learning for Face Verification in the Wild, CVPR 2014

## Classification Network

#### Application in face verification (IV)

LFW:97.35%



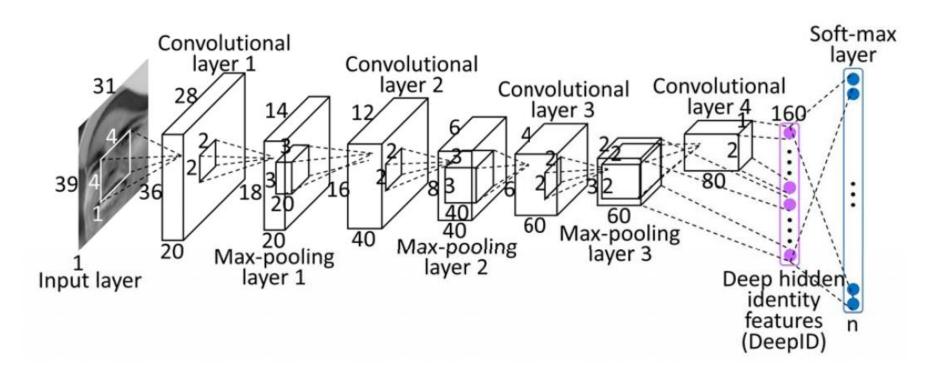
#### **Verification Metric:**

- 1)Cosine similarity
- 2) Weighted  $\chi^2$  distance  $\chi^2(f_1, f_2) = \sum_i w_i (f_1[i] f_2[i])^2 / (f_1[i] + f_2[i])$
- 3) Siamese network  $d(f_1, f_2) = \sum_i \alpha_i |f_1[i] f_2[i]|$

## Classification Network

Application in face verification (III)

LFW:97.45%



Face Verification: Joint Bayesian

## Classification & Siamese Network

Application in face verification (V)

LFW:99.15%

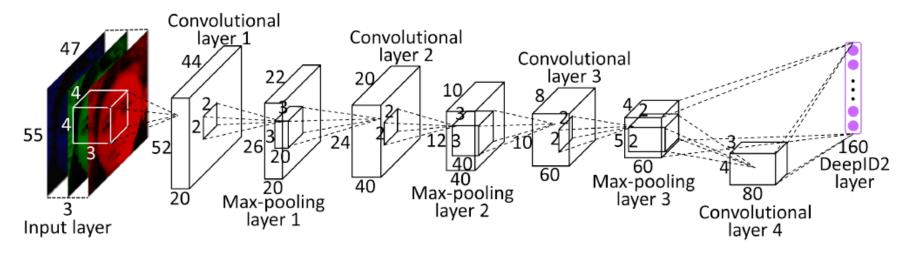


Figure 1: The ConvNet structure for DeepID2 extraction.

Deep Learning Face Representation by Joint Identification-Verification

## Classification & Siamese Network

Application in face verification (V)

#### 1. identification loss(cross-entropy)

$$Ident(f, t, \theta_{id}) = -\sum_{i=1}^{n} -p_i \log \hat{p}_i = -\log \hat{p}_t$$

#### 2. verification loss (contrastive)

$$\operatorname{Verif}(f_i, f_j, y_{ij}, \theta_{ve}) = \begin{cases} \frac{1}{2} \|f_i - f_j\|_2^2 & \text{if } y_{ij} = 1\\ \frac{1}{2} \max \left(0, m - \|f_i - f_j\|_2\right)^2 & \text{if } y_{ij} = -1 \end{cases}$$

#### 3. verification loss (cosine)

$$Verif(f_i, f_j, y_{ij}, \theta_{ve}) = \frac{1}{2} (y_{ij} - \sigma(wd + b))^2$$

where  $d = \frac{f_i \cdot f_j}{\|f_i\|_2 \|f_j\|_2}$  is the cosine similarity

## Classification & Siamese Network

#### Application in face verification (V)

Table 1: The DeepID2 learning algorithm.

**input**: training set  $\chi = \{(x_i, l_i)\}$ , initialized parameters  $\theta_c$ ,  $\theta_{id}$ , and  $\theta_{ve}$ , hyperparameter  $\lambda$ , learning rate  $\eta(t)$ ,  $t \leftarrow 0$ 

#### while not converge do

$$t \leftarrow t+1 \quad \text{sample two training samples } (x_i, l_i) \text{ and } (x_j, l_j) \text{ from } \chi$$

$$f_i = \text{Conv}(x_i, \theta_c) \text{ and } f_j = \text{Conv}(x_j, \theta_c)$$

$$\nabla \theta_{id} = \frac{\partial \text{Ident}(f_i, l_i, \theta_{id})}{\partial \theta_{id}} + \frac{\partial \text{Ident}(f_j, l_j, \theta_{id})}{\partial \theta_{id}}$$

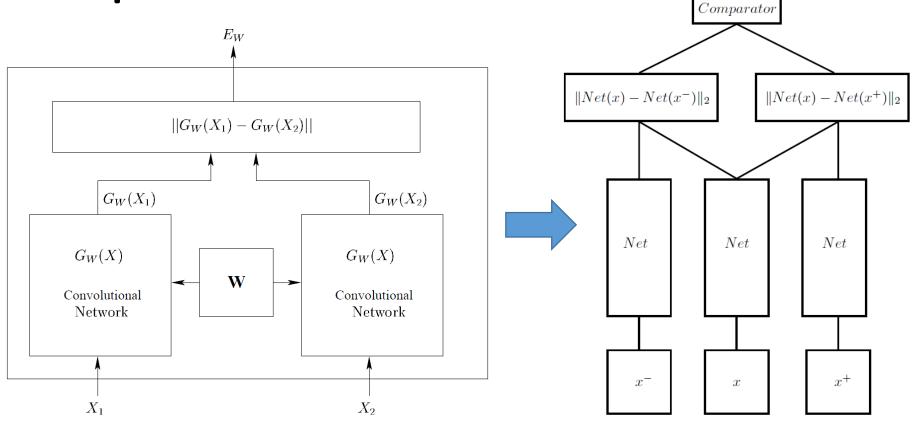
$$\nabla \theta_{ve} = \lambda \cdot \frac{\partial \text{Verif}(f_i, f_j, y_{ij}, \theta_{ve})}{\partial \theta_{ve}}, \text{ where } y_{ij} = 1 \text{ if } l_i = l_j, \text{ and } y_{ij} = -1 \text{ otherwise.}$$

$$\nabla f_i = \frac{\partial \text{Ident}(f_i, l_i, \theta_{id})}{\partial f_i} + \lambda \cdot \frac{\partial \text{Verif}(f_i, f_j, y_{ij}, \theta_{ve})}{\partial f_i}$$

$$\nabla f_j = \frac{\partial \text{Ident}(f_j, l_j, \theta_{id})}{\partial f_j} + \lambda \cdot \frac{\partial \text{Verif}(f_i, f_j, y_{ij}, \theta_{ve})}{\partial f_j}$$

$$\nabla \theta_c = \nabla f_i \cdot \frac{\partial \text{Conv}(x_i, \theta_c)}{\partial \theta_c} + \nabla f_j \cdot \frac{\partial \text{Conv}(x_j, \theta_c)}{\partial \theta_c}$$

$$\text{update } \theta_{id} = \theta_{id} - \eta(t) \cdot \theta_{id}, \theta_{ve} = \theta_{ve} - \eta(t) \cdot \theta_{ve}, \text{ and } \theta_c = \theta_c - \eta(t) \cdot \theta_c.$$
end while output  $\theta_c$ 



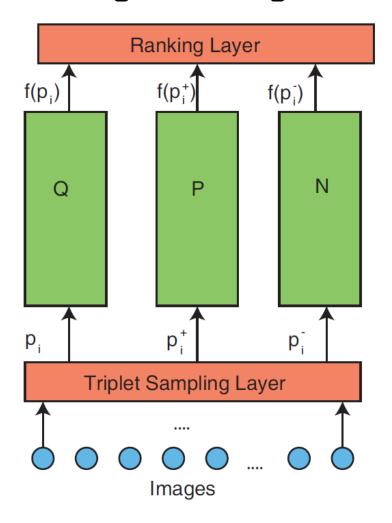
From Siamese to Triplet Network

## Application in Image ranking

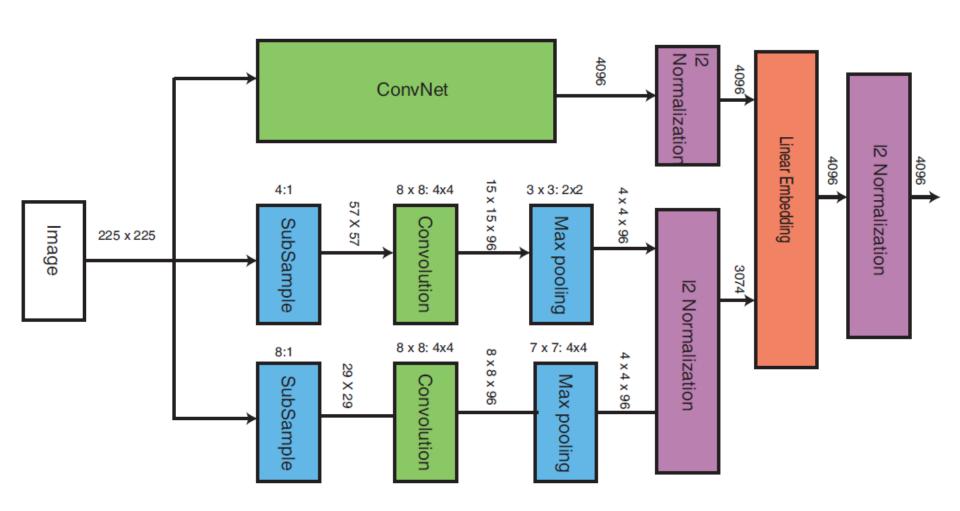


Sample images from the triplet dataset

#### Application in Image ranking



## Application in Image ranking



Jiang Wang, etc. Learning Fine-grained Image Similarity with Deep Ranking. CVPR 2014

#### Application in Image ranking

Distance

$$D(f(P), f(Q)) = ||f(P) - f(Q)||_2^2$$

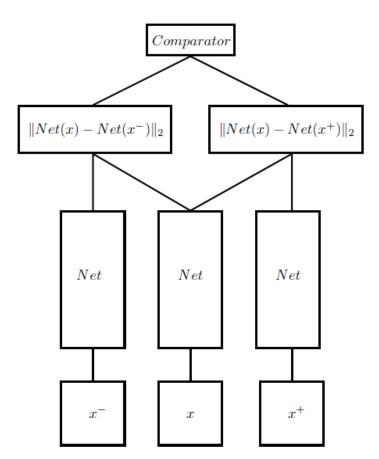
$$D(f(p_i), f(p_i^+)) < D(f(p_i), f(p_i^-)),$$
  
 $\forall p_i, p_i^+, p_i^- \text{ such that } r(p_i, p_i^+) > r(p_i, p_i^-)$ 

Hinge Loss

$$l(p_i, p_i^+, p_i^-) = \max\{0, g + D(f(p_i), f(p_i^+)) - D(f(p_i), f(p_i^-))\}$$

## Application in deep metric learning

$$TripletNet(x, x^{-}, x^{+}) = \begin{bmatrix} ||Net(x) - Net(x^{-})||_{2} \\ ||Net(x) - Net(x^{+})||_{2} \end{bmatrix} \in \mathbb{R}^{2}_{+}$$



SoftMax function is applied on both outputs

Elad Hoffer, etc. DEEP METRIC LEARNING USING TRIPLET NETWORK. Under review as a conference paper at ICLR 2015 http://arxiv.org/abs/1412.6622

## Application in deep metric learning



2D VISUALIZATION OF FEATURES of CIFAR10

## Conclusion

The loss function in Siamese Network is very important.

Mixed Network Architecture can improve the performance.

• Caffe implementation of Siamese Network: http://caffe.berkeleyvision.org/gathered/examples/siamese.html

# Thank you!